Computer Architecture Basics

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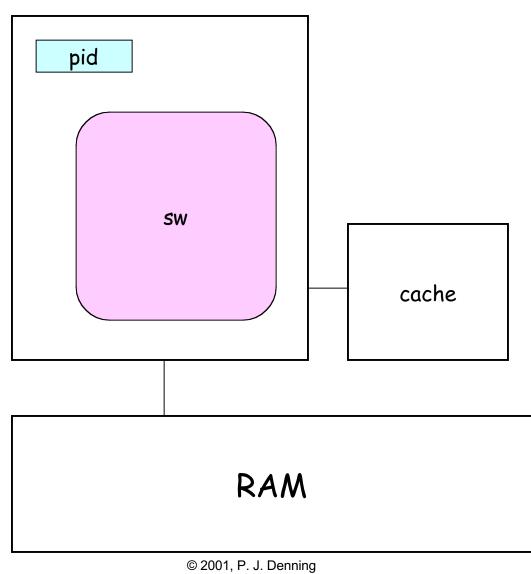
Elements

Interface with OS software and functions

- Basic CPU
- Basic I/O
- Cache
- Procedures
- Memory protection

- Privilege modes
- Interrupts
- Statewords
- Processes

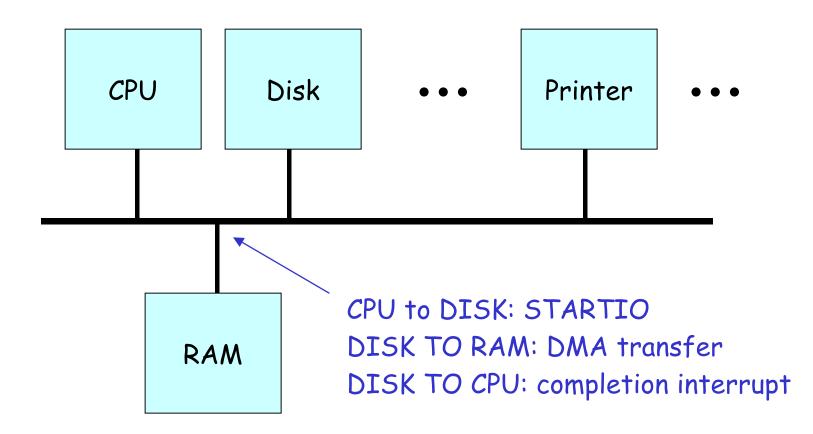




Basic CPU -- Stateword

- Arithmetic registers
- Address registers
- Instruction pointer register
- Supervisor/User mode flipflop
- Interrupt mask register
- Stack pointer register
- Stack environment registers
- Timer alarm clock

Basic I/O



Basic I/O

- STARTIO(i, j, a, b, rw, size)
 - Method 1: Package (a,b,rw,size) in packet from sender j to device i
 - Method 2: Place (a,b,rw,size) in device block in memory --- memory mapped I/O
- Transfer via Direct memory access (DMA)
- Finish with completion interrupt

Cache

Hold subset of RAM contents in fast local-access store

- Blocks of memory all of same size
 - RAM block = page
 - Cache block = slot
- RAM set = fixed set of pages mapping to a single slot; same number of pages in each set
- Cache holds one slot per set
- Index: table telling which page in each slot

Sets: 0 1 2 3

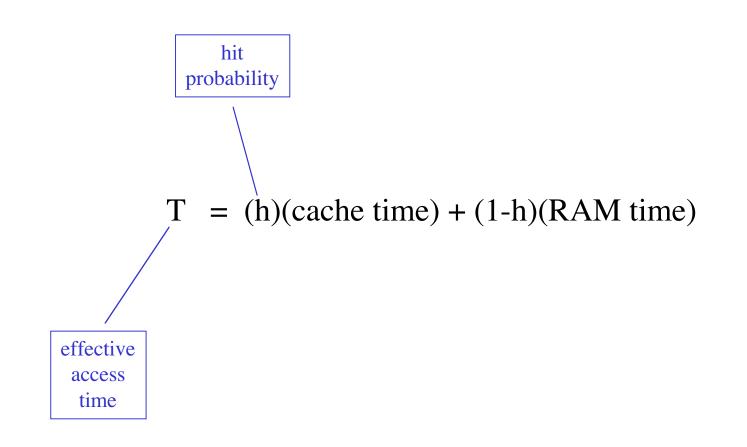
0	1	2	3
4	5	6	7
8	9	10	11
12	13	14	15

0 12	1 5	
2 2	³ 11	
cache		

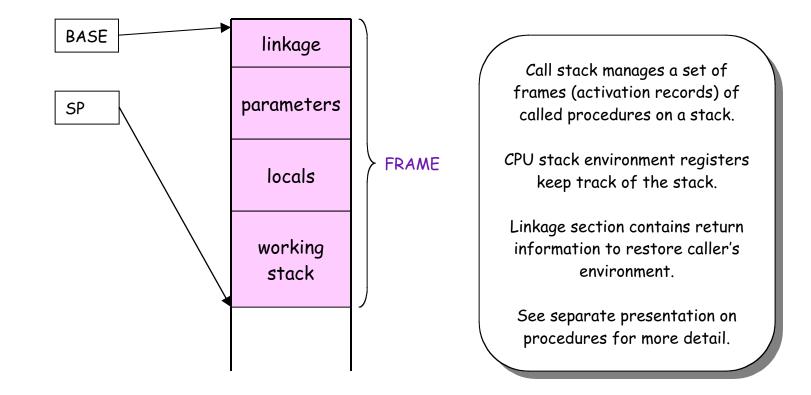
0	12
1	5
2	2
3	11

index

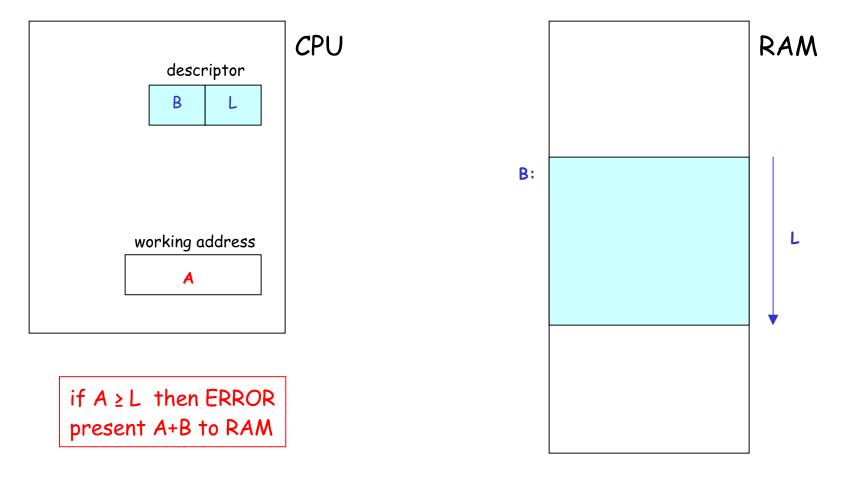
RAM



Procedure Call Stack



Memory Protection



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Interrupts

- Event detectors
- Interrupt mask bits
- Interrupt number
- Interrupt vector = interrupt handler handles
- Interrupt handler
- Interrupt parameter (passed in register or atop stack)
- System Call instruction

handle =

- entry point address
- + supervisor/user mode value
- + interrupt mask

CALL instruction uses handle to set IP, S, and M

Hardware Interrupt Dispatch

Interrupt signal

Select i = highest priority pending signal

CALL IH[i] (sets IP, S, M) and pass parameter

- Process: abstraction of running program
- Process = dynamic trace of IP moving through program code
- Process = sequence of statewords of a running program
- Process must have address space = context of code, data, and stack

- pid register in CPU = identity of process using CPU
- stateword of CPU = contents of all registers (except pid)
- PCB = process control block = sw + LINK
- Preset for processes 0, 1, 2, ..., N

- Ready list = FIFO of all CPU-ready pids
- RL = (h,t) descriptor linking ready PCB's
- SAVESW -- sw to PCB[pid]
- LOADSW -- PCB[RL.h].SW to CPU
- Context switch = (SAVESW, LOADSW)

- Create process (FORK) = initialize free PCB with SW, link to RL tail
- Delete process (JOIN) = mark PCB as free
- FL = (h,t) descriptor linking all free PCB's
- Process 0 = idle process, always at end of RL if LINK 0 is endmarker

Simple Scheduling (Round Robin)

- Clock interrupt switches CPU to next ready process
- Q = time quantum = max time for CPU to run in one process
- Clock interrupt handler:

```
disable
SAVESW
link pid to RL tail
set alarm clock = Q
LOADSW
enable
return
```

A more detailed description of these elements of process management can be found in the slides about time sharing.